## ebm-papst Mulfingen GmbH & Co. KG

4 CAFETY DECLU ATIONS AND INCORMATION

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## 1. SAFETY REGULATIONS AND INFORMATION

Read these operating instructions carefully before starting work on the device. Observe the following warnings to prevent malfunctions or danger to persons.

These operating instructions are to be regarded as part of the device. The device is only to be sold or passed on together with the operating instructions.

These operating instructions may be duplicated and distributed to inform about potential dangers and their prevention.

## 1.1 Hazard levels for warnings

These operating instructions use the following hazard levels to indicate potentially hazardous situations and important safety regulations:



#### **DANGER**

Indicates an imminently hazardous situation which will result in death or serious injury if the specified actions are not taken. Compliance with the instructions is imperative.

#### WARNING

Indicates a potentially hazardous situation which can result in death or serious injury if the specified actions are not taken. Exercise extreme caution while working.

## **CAUTION**

Indicates a potentially hazardous situation which can result in minor or moderate injury or damage to property if the specified actions are not taken.

## NOTE

A potentially harmful situation can occur and, if not avoided, can lead to property damage.

## 1.2 Staff qualifications

The device may only be transported, unpacked, installed, operated, maintained and otherwise used by suitably qualified, trained and authorized technical staff.

Only authorized specialists are permitted to install the device, to carry out a test run and to perform work on the electrical installation.

#### 1.3 Basic safety rules

The safety hazards associated with the device must be assessed again following installation in the final product.

The locally applicable industrial safety regulations are always to be observed when working on the device.

Keep the workplace clean and tidy. Untidiness in the work area increases the risk of accidents.

Note the following when working on the device:

⇒ Do not perform any modifications, additions or conversions on the device without the approval of ebm-papst.

# 1.4 Voltage

- Check the device's electrical equipment at regular intervals; see Chapter 6.3 Safety inspection.
- ⇒ Replace loose connections and defective cables immediately.



# DANGER

Electrically charged device

Risk of electric shock

→ When working on an electrically charged device, stand on a rubber mat.







#### WARNING

# Live terminals and connections even with device switched off

Electric shock

→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

#### CAUTION

# In the event of a fault, the rotor and the impeller will be energized

The rotor and the impeller have basic insulation.

 $\rightarrow$  Do not touch the rotor and impeller once installed.

#### CAUTION

If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.

Risk of injury

- → Keep out of the device's danger zone.
- → When working on the device, switch off the line voltage and ensure that it cannot be switched back on.
- → Wait until the device comes to a stop.
- After working on the device, remove any tools or other objects from the device.

# 1.5 Safety and protective features



#### **DANGER**

# Guard missing and guard not functioning

Without a guard, hands may become caught up in the device during operation for example, resulting in serious injury. Loose parts or items of clothing could be drawn in.

- → The device is a built-in component. As the owner, you are responsible for ensuring that the device is adequately safeguarded.# Operate the device only with a fixed protective device and guard grill.
- $\rightarrow$  Stop the device immediately if a protective device is found to be missing or ineffective.

## 1.6 Electromagnetic radiation

Interference from electromagnetic radiation is possible, e.g. in conjunction with open- and closed-loop control devices.

If impermissible radiation levels occur following installation, appropriate shielding measures have to be taken by the user.

#### NOTE

Electrical or electromagnetic interference after installing the device in customer equipment.

→ Verify that the entire setup is EMC-compliant.

## 1.7 Mechanical movement



## **DANGER**

#### Rotating device

Risk of injury to body parts coming into contact with the rotor or the impeller.

- → Secure the device against accidental contact.
- → Before working on the system/machine, wait until all parts have come to a standstill.

#### **WARNING**

#### Rotating device

Long hair and dangling items of clothing, jewelry and the like can become entangled and be pulled into the device. Injuries can result

- → Do not wear any loose-fitting or dangling clothing or jewelry while working on rotating parts.
- → Protect long hair with a cap.

#### 1.8 Emissions

#### **WARNING**

Depending on the installation and operating conditions, the sound pressure level may exceed 70 dB(A).

Risk of noise-induced hearing loss

- → Take appropriate technical safety measures.
- → Protect operating personnel with appropriate safety equipment such as hearing protection.
- → Also observe the requirements of local agencies.

#### 1.9 Hot surface



#### CAUTION

# High temperature on electronics housing

Risk of burns

→ Ensure sufficient protection against accidental contact.

## 1.10 Transport



#### WARNING

**Transporting the fan**Injuries from tipping or slipping, damage to the fan

→ Always transport the fan with care and in its original packaging. #Impact, e.g. if set down too hard or at an angle, can lead to bearing damage or impeller deformations. #It must be ensured that the fans cannot tip over during transportation and handling. #Secure the fan(s) e.g. with a lashing strip to stop anything slipping or tipping.

# 1.11 Storage

- Store the device, partially or fully assembled, in a dry place, protected against the weather and free from vibration, in the original packaging in a clean environment.
- ⇒ Protect the device against environmental effects and dirt until final installation.
- We recommend storing the device for no longer than one year in order to guarantee trouble-free operation and the longest possible service life.
- ⇒ Even devices explicitly intended for outdoor use are to be stored as described prior to commissioning.
- ⇒ Maintain the storage temperature, see Chapter 3.6 Transport and storage conditions.





# n of the original operating instructions

# Operating instructions

## 2. INTENDED USE

The device is exclusively designed as a built-in device for conveying air according to its technical data.

Any other usage above and beyond this does not conform with the intended purpose and constitutes misuse of the device.

Customer equipment must be capable of withstanding the mechanical and thermal stresses that can arise from this product. This applies for the entire service life of the equipment in which this product is installed.

#### Intended use also includes

- Using the device only in power systems with grounded neutral (TN/ TT power systems).
- The device is to be used in networks with network quality characteristics as per EN 50160.
- Use of the device in stationary systems only.
- · Performance of all maintenance work.
- Conveying air at an ambient air pressure between 800 mbar and 1050 mbar.
- Using the device within the permitted ambient temperature range; see Chapter 3.6 Transport and storage conditions and Chapter 3.2 Nominal data.
- Operating the device with all protective devices.
- Following the operating instructions.

#### Improper use

In particular, operating the device in the following ways is prohibited and could be hazardous:

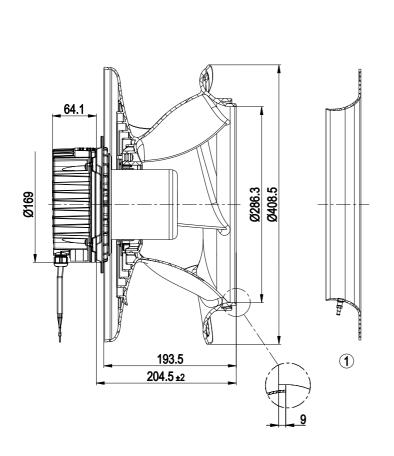
- Operating the device in an unbalanced state, e.g. due to dirt deposits or ice formation.
- Resonant operation, operation with severe vibration. This also includes vibration transmitted to the fan from the customer installation.
- Operation in medical equipment with a life-sustaining or life-support function.
- Conveying solids in the flow medium.
- Painting the device
- · Connections (e.g. screws) coming loose during operation.
- Conveying air that contains abrasive particles.
- Conveying highly corrosive air, e.g. salt spray. Exception: devices designed for salt spray and correspondingly protected.
- Conveying air with high dust content, e.g. suctioning off sawdust.
- Operating the device close to flammable materials or components.
- Operating the device in an explosive atmosphere.
- Using the device as a safety component or to perform safety-related functions.
- Operation with completely or partially disassembled or manipulated protective devices.
- In addition, all applications not listed among the intended uses.

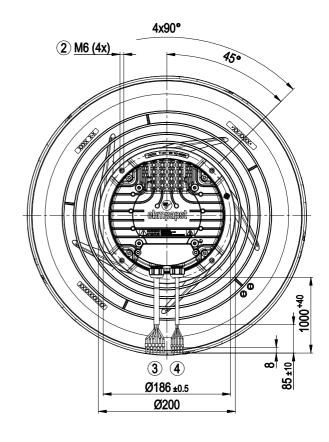




# 3. TECHNICAL DATA

# 3.1 Product drawing



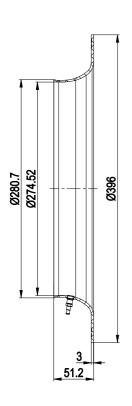


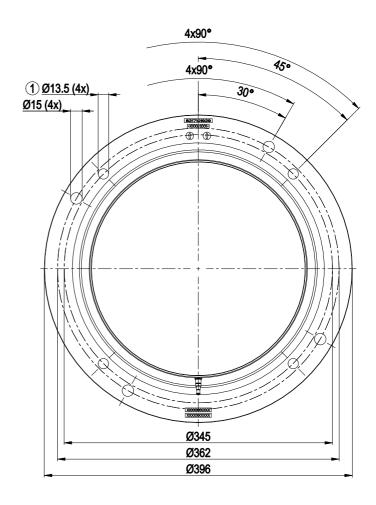
All dimensions in mm.

1	Accessory part: Inlet ring 8217102241 with pressure tap (k-factor: 190) (not included in scope of delivery)		
2	Max. clearance for screw 16 mm		
3	Cable PVC AWG18		
	6x wire-end ferrule		
4	Cable PVC AWG22		
	5x wire-end ferrule		









All dimensions in mm.

		Inlet ring 8217102241 with pressure tap (k-factor: 190)
Ī	1	Fastening holes for FlowGrid 00400-2-2957 (not included in scope of delivery) are provided and must be subsequently opened as required



# Translation of the original operating instruction

# Operating instructions

# 3.2 Nominal data

Motor	E08423-65
Phase	3~
	ŭ
Nominal voltage / VAC	400
Nominal voltage	380 480
range / VAC	
Frequency / Hz	50/60
Method of obtaining	ml
data	
Status	prelim.
Speed (rpm) / min-1	2480
Power consumption / W	1400
Current draw / A	2.2
Min. ambient	-40
temperature / °C	
Max. ambient	40
temperature / °C	

ml = Max. load  $\cdot$  me = Max. efficiency  $\cdot$  fa = Free air cs = Customer specification  $\cdot$  ce = Customer equipment

# 3.3 Data according to Commission Regulation (EU) 327/2011

	Actual	Reg. 2015
01 Overall efficiency ηes / %	68.5	53
02 Measurement category	Α	<b>'</b>
03 Efficiency category	Static	
04 Efficiency grade N	77.5	62
05 Variable speed drive	Yes	•
06 Year of manufacture	product's rating	
07 Manufacturer		ngen GmbH & Co. KG urt of registration) Stuttgart · gen
08 Type	8300100465	
09 Power consumption Ped / kW	1.37	
09 Air flow q <sub>v</sub> / m³/h	5035	
09 Pressure increase total pfs / Pa	628	
10 Speed (rpm) n / min-1	2480	
11 Specific ratio*	1.01	
12 Recycling/disposal		ecycling and disposal is operating instructions.
13 Maintenance		nstallation, operation and provided in the operating
14 Additional components	efficiency that a	ed to calculate the energy re not apparent from the ategory are detailed in the

<sup>\*</sup> Specific ratio = 1 + pfs / 100 000 Pa

Data obtained at optimum efficiency level. The efficiency values displayed for achieving conformity with the Ecodesign Regulation EU 327/2011 has been reached with defined air duct components (e.g. inlet rings). The dimensions must be requested from ebm-papst. If other air conduction geometries are used on the installation side, the ebm-papst evaluation loses its validity/the conformity must be confirmed again. The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2 (2a) (motors completely integrated into a product).

# 3.4 Technical description

Size	400 mm
Motor size	84
Rotor surface	Painted black
	Die-cast aluminum
Electronics housing material	Die-cast aluminum
	DD plantin
Impeller material	PP plastic
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) /	H1
Environmental (H)	
protection class	
Ambient temperature	Occasional start-up at temperatures
note	between -40°C and -25°C is permitted.
	For continuous operation at ambient
	temperatures below -25°C (such as
	refrigeration applications), use must be
	made of a fan design with special low-
1 ( 11 () ) ()	temperature bearings.
Installation position	Shaft horizontal or rotor on bottom; rotor
0 1 "	on top on request
Condensation	On rotor side
drainage holes	04
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA
	- Output 10 VDC, max. 10 mA - Operation and alarm display
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting)
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for
	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure
Technical features  Touch current	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - MODBUS V5.1 - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection <= 3.5 mA





Subject to change

# Translation of the original operating instruction

# Operating instructions

Protection class	I; If a protective earth is connected by
assignment	the customer
	This component for installation may
	have several local protection classes.
	This information relates to this
	component's basic design.
	The final protection class is based on
	the component's intended installation and
	connection.
Conformity with	EN 61800-5-1; UKCA; CE
standards	
Approval	UL 1004-7 + 60730-1; EAC; CSA
	C22.2 No. 77 + CAN/CSA-E60730-1

⇒ Use the device in accordance with its degree of protection.

# Information on surface quality

The surfaces of the products conform to the generally applicable industrial standard. The surface quality may change during the production period. This has no effect on strength, dimensional stability and dimensional accuracy.

The color pigments in the paints used perceptibly react to UV light over the course of time. The product is to be protected against UV radiation to prevent the formation of patches and fading. Changes in color are not a reason for complaint and are not covered by the warranty. UV radiation in the frequency range and the intensity of natural solar radiation has no effect on the technical properties of the products.

# 3.5 Mounting data

Further mounting data can be taken from the product drawing or Chapter 4.1 Mechanical connection as required.

Strength class of	8.8	
screws		

For screw clearance, see Chapter 3.1 Product drawing

Secure the screws against unintentional loosening (e.g. use self-locking screws).

## 3.6 Transport and storage conditions

Max. permitted ambient temp. for motor (transport/ storage)	+80 °C
Min. permitted ambient temp. for motor (transport/ storage)	-40 °C

## 3.7 Electromagnetic compatibility



If several devices are connected in parallel on the supply side so that the line current of the arrangement is in the range 16 - 75 A, this arrangement conforms to IEC 61000-3-12, provided that the short-circuit power Ssc at the connection point of the customer system to the public power grid is greater than or equal to 250 times the rated output of the arrangement. It is the responsibility of the installation engineer or operator/owner of the device to ensure, if necessary after consultation with the network operator, that this device is only connected to a connection point with an Ssc value greater than or equal to 250 times the rated output of the arrangement.

# 4. CONNECTION AND STARTUP

#### 4.1 Mechanical connection



## **CAUTION**

# Cutting and crushing hazard when removing fan from packaging



- → Carefully remove the device from its packaging, by the fan impeller. Strictly avoid shocks.
- → Wear safety shoes and cut-resistant safety gloves.



#### NOTE

## Damage to the device from vibration

Bearing damage, shorter service life

- → The fan must not be subjected to force or excessive vibration from sections of the installation.
- → If the fan is connected to air ducts, the connection should be isolated from vibration, e.g. using compensators or similar elements
- Ensure stress-free attachment of the fan to the substructure.
- ⇒ Check the device for transport damage. Damaged devices are not to be installed
- ⇒ Install the undamaged device in accordance with your application.



#### **CAUTION**

# Possible damage to the device

If the device slips during installation, serious damage can result.

- → Ensure that the device is securely positioned at its place of installation until all fastening screws have been tightened.
- · The fan must not be strained on fastening.

## 4.2 Electrical connection



## **DANGER**

## Voltage on the device

Electric shock

- → Always connect a protective earth first.
- $\rightarrow$  Check the protective earth.



#### DANGER

#### Faulty insulation

Risk of fatal injury from electric shock

- → Use only cables that meet the specified installation regulations for voltage, current, insulation material, capacity, etc.
- → Route cables so that they cannot be touched by any rotating parts.



#### **DANGER**

Electrical charge (>50  $\mu$ C) between phase conductor and protective earth connection after switching off supply with multiple devices connected in parallel.

Electric shock, risk of injury

→ Ensure sufficient protection against accidental contact. Before working on the electrical hookup, short the supply and PE connections.





# Translation of the original operating instructions

# Operating instructions

## **CAUTION**

#### Voltage

The fan is a built-in component and has no disconnecting switch.

- Only connect the fan to circuits that can be switched off with an all-pole disconnection switch.
- → When working on the fan, secure the system/machine in which the fan is installed so as to prevent it from being switched back on

#### NOTE

## Device malfunctions possible

Route the device's control lines separately from the supply line.

→ Maintain the greatest possible clearance. Recommendation: clearance > 10 cm (separate cable routing)

#### NOTE

#### Water ingress into wires or cables

Water ingress at the customer end of the cable can damage the device

→ Make sure the end of the cable is connected in a dry environment.



Only connect the device to circuits that can be switched off with an all-pole disconnection switch.

#### 4.2.1 Requirements

- Check whether the information on the nameplate matches the connection data.
- Before connecting the device, make sure the power supply matches the device voltage.
- Only use cables designed for the current level indicated on the nameplate.

For determining the cross-section, note the sizing criteria according to EN 61800-5-1. The protective earth must have a cross-section equal to or greater than that of the phase conductor.

We recommend the use of 105 °C cables. Ensure that the minimum cable cross-section is at least

AWG 26 / 0.13 mm<sup>2</sup>.

outside diameter of the cable.

 Note the following when routing the cables:
 For permanently installed lines, the bending radius must be at least four times the outside diameter of the cable.
 For movable lines, the bending radius must be at least 15 times the

#### Protective earth contact resistance according to EN 61800-5-1

Compliance with the resistance specifications according to EN 61800-5-1 for the protective earth connection circuit must be verified in the end application. Depending on the installation situation, it may be necessary to connect an additional protective earth conductor by way of the extra protective earth terminal provided on the device. The protective earth terminal is located on the housing and provided with a protective earth symbol and a hole.

## 4.2.2 Supply connection and fuses

Assignment of supply cable cross-sections and their required fuses (line protection only, no equipment protection).

Nominal voltage	Fuse		Automatic circuit breaker	Cable cross-section	Cable cross-section
	VDE	UL	VDE	mm²	*AWG
3/PE AC 380-480 VAC	16 A	15 A	C16A	1.5	16
3/PE AC 380-480 VAC	20 A	20 A	C20A	2.5	14
3/PE AC 380-480 VAC	25 A	25 A	C25A	4.0	12

<sup>\*</sup> AWG = American Wire Gauge

#### 4.2.3 Reactive currents



Because of the EMC filter integrated for compliance with EMC limits (interference emission and immunity to interference), reactive currents can be measured in the supply line even when the motor is at a standstill and the line voltage is switched on.

- The values are typically in the range < 250 mA</li>
- At the same time, the effective power in this operating state (operational readiness) is typically < 5 W.</li>

## 4.2.4 Residual current circuit breaker (RCCB)



If the use of a residual current device (RCD) is required in your installation, only AC/DC-sensitive residual current devices (type B or B+) are permissible. As with variable frequency drives, residual current devices cannot provide personal safety while operating the device. When the device power supply is switched on, pulsed charging currents from the capacitors in the integrated EMC filter can lead to the instant tripping of residual current devices. We recommend the use of residual current circuit breakers (RCCB) with a trip threshold of 300 mA and delayed tripping (super-resistant, characteristic K).

#### 4.2.5 Leakage current



For asymmetrical power systems or if a phase fails, the leakage current can increase to a multiple of the nominal value.

## 4.2.6 Locked-rotor protection



Due to the locked-rotor protection, the starting current (LRA) is equal to or less than the nominal current (FLA).





VBS0400CTPMS

# Operating instructions

# 4.3 Connecting the cables

The device has external leads.

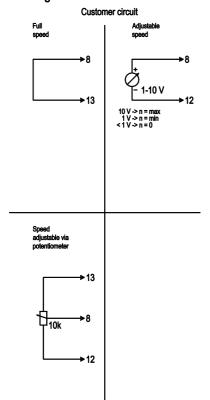
- ⇒ First connect the "PE" (protective earth).
- Connect the cables according to your application. When doing so, observe Chapter 4.4 Connection diagram.

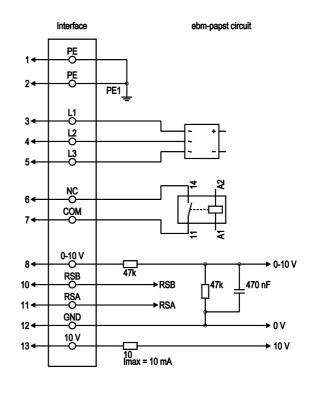






# 4.4 Connection diagram





Drawing preliminary!

No.	Conn.	Designation	Color	Function/assignment	
1	1, 2	PE	green/	Protective earth	
			yellow		
1	3	L1	black	Power supply	
1	4	L2	black	Power supply	
1	5	L3	black	Power supply	
1	6	NC	white 1	Status relay, floating status contact, break for failure,	
				contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on supply side and basic insulation on control interface side	
1	7	СОМ	white 2	Status relay, floating status contact, break for failure,	
				contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on supply side and basic	
				insulation on control interface side	
2	8	0-10V	yellow	Analog input (set value), 0-10 V, Ri = 100 kΩ, adjustable curve, SELV	
2	10	RSB	brown	RS485 interface for MODBUS, RSB; SELV	
2	11	RSA	white	RS485 interface for MODBUS, RSA; SELV	
2	12	GND	blue	Reference ground for control interface, SELV	
2	13	+10V	red	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for	
				external devices (e.g. pot), SELV	
				fixed voltage input 24 VDC for setting parameters via MODBUS without line voltage supply	



## 8300100465

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# Operating instructions

## 4.5 Checking connections

- ⇒ Ensure isolation from supply (all phases).
- ⇒ Make sure a restart is impossible
- Check the cables for proper fit.

# 4.6 Switching on the device

The device may only be switched on if it has been installed properly and in accordance with its intended use, including the required safety mechanisms and professional electrical hookup. This also applies for devices which have already been equipped with plugs and terminals or similar connectors by the customer.



# WARNING Hot motor housing

Risk of fire

- → Ensure that no combustible or flammable materials are located close to the fan.
- ⇒ Before switching on, check the device for visible external damage and make sure the protective devices are functional.
- Check the fan's air flow paths for foreign matter and remove any foreign matter found.
- Apply the nominal supply voltage.
- ⇒ Start the device by changing the input signal.



#### NOTE

#### Damage to the device from vibration

Bearing damage, shorter service life

- → Low-vibration operation of the fan must be ensured over the entire speed control range.
- → Severe vibration can arise for instance from inexpert handling, transportation damage and resultant imbalance or be caused by component or structural resonance.
- Speed ranges with excessively high vibration levels and possibly resonant frequencies must be determined in the course of fan commissioning.
- → Either run through the resonant range as quickly as possible with speed control or find another remedy.
- → Operation with excessively high vibration levels can lead to premature failure.
- → The maximum permissible vibration severity must not exceed 3.5 mm/s and should be checked at intervals of 6 months. #It is to be determined at the motor mount at the motor support plate at least in axial direction and transversely to this. #Measurement of the vibration in all three axes is recommended and should be performed over the entire speed range in order to obtain a complete picture of the vibrations occurring in the application, see Chapter 6. Maintenance, malfunctions, possible causes and remedies.

# 4.7 Switching off the device

Switching off the device during operation:

- ⇒ Switch off the device via the control input.
- Do not switch the motor (e.g. in cyclic operation) on and off via power supply.

Switching off the device for maintenance:

⇒ Switch off the device via the control input.

- ⇒ Do not switch the motor (e.g. in cyclic operation) on and off via power supply
- ⇒ Disconnect the device from the power supply.
- ⇒ When disconnecting, be sure to disconnect the ground connection last.

#### 5. INTEGRATED PROTECTIVE FEATURES

The integrated protective functions cause the motor to switch off automatically in the event of the faults described in the table.

Fault	Safety feature description/ function
Rotor position detection error	An automatic restart follows.
Blocked rotor	⇒ After the blockage is removed, the motor restarts automatically.
Line undervoltage (line voltage outside of permitted nominal voltage range)	⇒ If the line voltage returns to permitted values, the motor restarts automatically.
Phase failure	A phase of the supply voltage fails for at least 5 s.  ⇒ When all phases are correctly supplied again, the motor automatically restarts after 10-40 s.





# 6. MAINTENANCE, MALFUNCTIONS, POSSIBLE CAUSES AND REMEDIES

Do not perform any repairs on your device. Send the device to ebmpapst for repair or replacement.



#### WARNING

Live terminals and connections even with device switched off

Electric shock

→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

#### CAUTION

If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.

Risk of injury

- → Keep out of the device's danger zone.
- → When working on the device, switch off the line voltage and ensure that it cannot be switched back on.
- → Wait until the device comes to a stop.
- → After working on the device, remove any tools or other objects from the device.



#### NOTE

If the device is not operated for a lengthy period in installed condition in a dry environment, it is to be started up and operated at full speed for one hour at least every four months. If the device is not operated for a lengthy period in installed condition in a damp environment (e.g. outdoors), it is to be started up and operated at full speed for at least two hours once a month to move the bearings and allow any condensate that may have ingressed to evaporate.

Malfunction/fault	Possible cause	Possible remedy	
Impeller not running smoothly	Imbalance in rotating parts	Clean the device; replace it if imbalance persists after cleaning. Make sure no weight clips are removed during cleaning.	
Audible grinding or scraping noise during operation	Impeller grinds on the inlet ring	Align inlet ring centrally with the impeller	
Motor not turning	Mechanical blockage	Switch off, isolate from supply and remove mechanical blockage.	
	Line voltage faulty	Check line voltage, restore power supply. Attention! The error message resets automatically. Device restarts automatically without warning.	
	Faulty connection	Isolate from supply, correct connection; see connection diagram.	
	Broken motor winding	Replace device	

Thermal overload	Allow motor to cool	
protector activated	off, locate and rectify	
	cause of error,	
	release restart lockout	
	if necessary	
Deficient cooling	Improve cooling. Let	
	the device cool down.	
	To reset the error	
	message, switch off	
	the line voltage for at	
	least 25 s and then	
	switch it on again.	
	Alternatively, reset	
	the error message by	
	applying a control	
	signal of < 0.5 V to	
	Din1 or by shorting	
	Din1 to GND.	
Ambient temperature	Reduce the ambient	
too high	temperature. Let the	
	device cool down.	
	To reset the error	
	message, switch off	
	the line voltage for at	
	least 25 s and then	
	switch it on again.	
	Alternatively, reset	
	the error message by	
	applying a control	
	signal of < 0.5 V to	
	Din1 or by shorting	
	Din1 to GND.	
Impermissible point of	Correct the operating	
operation (e.g. back	point. Let the device	
pressure too high)	cool down.	
. ,	To reset the error	
	message, switch off	
	the line voltage for at	
	least 25 s and then	
	switch it on again.	
	Alternatively, reset	
	the error message by	
	applying a control	
	signal of < 0.5 V to	
	Din1 or by shorting	
	Din1 to GND.	



In the event of further malfunctions, contact ebm-papst.

# 6.1 Vibration testing

Checking of fan for mechanical vibration based on ISO 14694.
Recommendation: Every 6 months. Max. vibration severity is 3.5 mm/s, measured at the motor fastening diameter on the motor support plate in the direction of the motor axis of rotation and perpendicular to this.





# **8300100465** VBS0400CTPMS

# Operating instructions

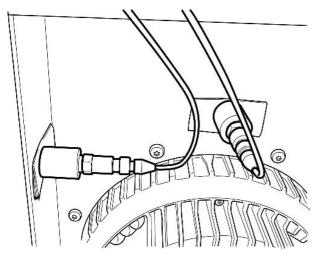


Fig. 1: Example illustrating vibration measurement. The arrangement of the sensors depends on the device concerned and the installation situation.

# 6.2 Cleaning

To ensure a long service life, check the fans regularly for proper operation and soiling. The frequency of checking is to be adapted accordingly depending on the degree of soiling.



# DANGER Risk of injury from rotating fan.

- → Only clean when not in motion. Do not disconnect the fan from the power supply, just switch it off via the control input. This will prevent start-up of the fan.
- ⇒ Dirt deposits on the motor housing can cause overheating of the motor.
- Soiling of the impeller can cause vibration that will shorten the service life of the fan.
- ⇒ Severe vibration can destroy the fan.
- ⇒ In such cases, switch off the fan immediately and clean it.
- The preferred method of cleaning is dry cleaning, e.g. using compressed air.
- ⇒ Do not use aggressive cleaning agents!

#### NOTE

#### Damage to the device during cleaning

Malfunction possible

- → Do not clean the device using a high-pressure cleaner.# Do not use acid, alkali or solvent-based cleaning agents.
- → Do not use any pointed or sharp-edged objects for cleaning.
- ⇒ Completely remove any cleaning agents used.
- If severe corrosion is visible on load-bearing or rotating parts, switch off the device immediately and replace it.
- ⇒ Repair of load-bearing or rotating parts is not permitted!
- Operate the fan for 2 hours at maximum speed so that any water that has ingressed can evaporate.
- If cleaning does not eliminate vibrations, the fan may need to be rebalanced. To have it rebalanced, contact ebm-papst.
- ⇒ The fan is equipped with maintenance-free ball bearings. The lifetime lubrication of the ball bearings is designed for a service life of 40,000 hours.

- ⇒ If bearing replacement is necessary after that period, contact ebmnanst
- ⇒ Adapt the maintenance intervals to the actual level of dust exposure.

## 6.3 Safety inspection

#### **NOTE**

## High-voltage test

The integrated EMC filter has Y capacitors. The tripping current is exceeded when AC testing voltage is applied.

→ Test the device with DC voltage when you perform the legally required high-voltage test. The voltage to be used corresponds to the peak value of the AC voltage required by the standard.

What to check	How to check	How often	What action?
Contact	Visual inspection	At least every	Repair or
protection		6 months	replacement of
cover for			device
intactness or			
damage			
Device for	Visual inspection		Replacement of
damage to		6 months	device
blades and			
housing			
Fastening the	Visual inspection	At least every	Fasten
cables	\ r \ \ \ r \ \ \ r \ \ r \ \ r \ \ r \ \ r \ \ r \ \ \ r \ \ \ r \ \ \ \ r \ \ \ r \ \ \ r \ \ \ r \ \ \ r \ \ \ r \ \ \ \ r \ \ \ \ r \ \ \ \ r \ \ \ \ \ \ \ r \ \ \ \ r \ \ \ \ r \	6 months	
Fastening the	Visual inspection		Fasten
protective earth terminal		6 months	
Insulation of	\ f: 1 ! +!	A414	Davidson salata
cables for	Visual inspection	At least every 6 months	Replace cables
		o monuis	
Impeller for	Visual inspection	At least even	Clean impeller
wear/deposits/	visuai irispectiori	At least every 6 months	or replace device
corrosion and		O IIIOIIIIIS	or replace device
damage			
Condensation	Visual inspection	At least every	Open holes
drainage holes	Vioudi mopodion	6 months	Opon noice
for clogging,		o monaro	
where necessary			
Abnormal	acoustic	At least every	Replace device
bearing noise		6 months	
Vibration test	Vibration tester,	Recommended	Clean impeller
	start-up or	every 6 months	or replace device
	deceleration		
	measurement		

## 6.4 Disposal

For ebm-papst, environmental protection and resource preservation are top priority corporate goals.

ebm-papst operates an environmental management system which is certified in accordance with ISO 14001 and rigorously implemented around the world on the basis of German standards.

Right from the development stage, ecological design, technical safety and health protection are fixed criteria.

The following section contains recommendations for ecological disposal of the product and its components.





# 6.4.1 Country-specific legal requirements



#### NOTE

## Country-specific legal requirements

Always observe the applicable country-specific legal regulations with regard to the disposal of products or waste occurring in the various phases of the life cycle. The corresponding disposal standards are also to be heeded.

#### 6.4.2 Disassembly

Disassembly of the product must be performed or supervised by qualified personnel with the appropriate technical knowledge. The product is to be disassembled into suitable components for disposal employing standard procedures for motors.



#### WARNING

Heavy parts of the product may drop off. Some of the product components are heavy. These components could drop off during disassembly.

This can result in fatal or serious injury and material damage.

→ Secure components before unfastening to stop them falling.

#### 6.4.3 Component disposal

The products are mostly made of steel, copper, aluminum and plastic. Metallic materials are generally considered to be fully recyclable. Separate the components for recycling into the following categories:

- Steel and iron
- Aluminum
- Non-ferrous metal, e.g. motor windings
- Plastics, particularly with brominated flame retardants, in accordance with marking
- Insulating materials
- Cables and wires
- Electronic scrap, e.g. circuit boards

Only ferrite magnets and not rare earth magnets are used in external rotor motors from ebm-papst Mulfingen GmbH & Co. KG.

Ferrite magnets can be disposed of in the same way as normal iron and steel.

Electrical insulating materials on the product, in cables and wires are made of similar materials and are therefore to be treated in the same

The materials concerned are as follows:

- · Miscellaneous insulators used in the terminal box
- Power cables
- Cables for internal wiring
- Electrolytic capacitors

Dispose of electronic components employing the proper procedures for electronic scrap.



→ Please contact ebm-papst for any other questions on disposal.



